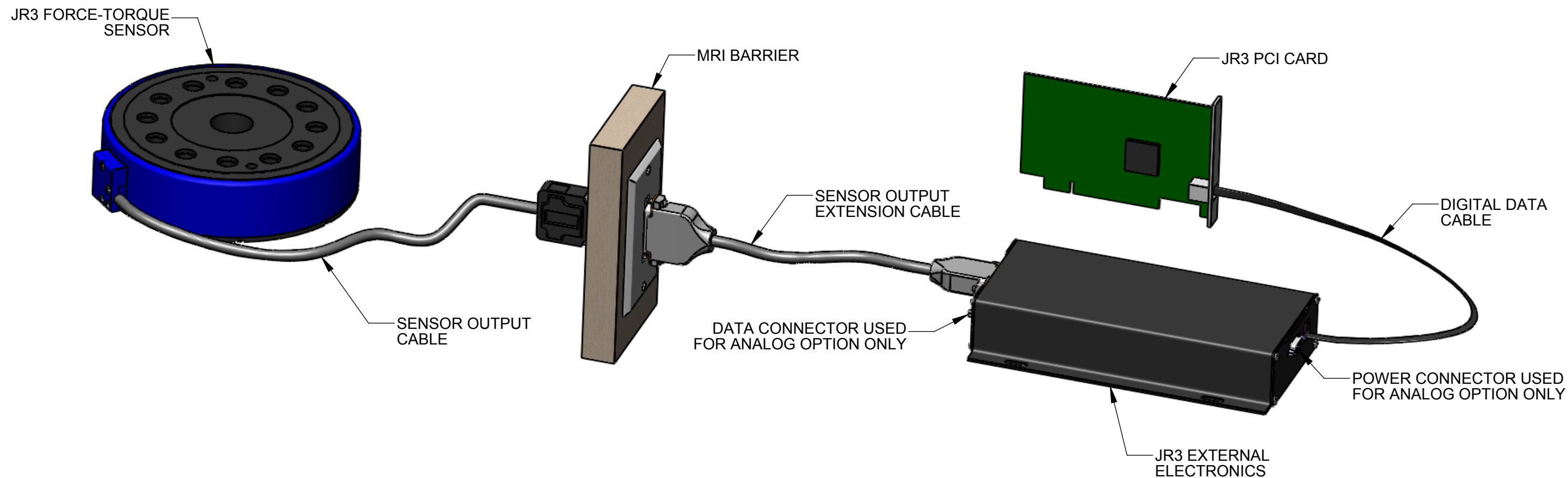


REVISIONS				
REV	DESCRIPTION	REV BY	DATE	APPROVED
-	INITIAL RELEASE	N/A	05-06-2015	G. SAKONA



NOTES:
 1. DIAGRAM IF FOR REFERENCE ONLY, SOME DETAILS MAY BE DIFFERENT.

TITLE: JR3 FORCE-TORQUE SENSOR SYSTEM, MRI CONFIGURATION, DIGITAL OUTPUT			
TOLERANCES: (UNLESS OTHERWISE NOTED) .XX = ±.010in .XXX = ±.005in .XXXX = ±.001in ANGLES = ±0.1°		DWG SIZE: B	DRAWN BY: K. NIELSEN
		SCALE: NOT TO SCALE	DWG NO: 9615
			REV: -
JR3, INC. WOODLAND, CA 95776			SHEET 1 OF 1